

AD-A191 892

CONVERGENCE RATE OF CODES FOR NUMERICAL QUADRATURE  
TECHNIQUES FOR CLASSICAL RAY TRACING(U) NAVAL OCEAN  
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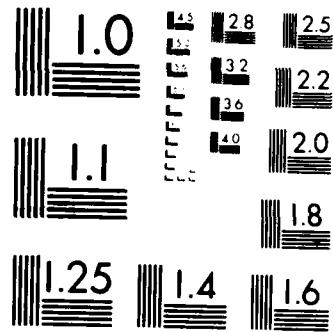
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REF ID: A6522  
DTIC DOCUMENTATION PAGE  
ELECTED

2a SECURITY CLASSIFICATION AUTHORITY

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1b RESTRICTIVE MARKINGS

2b DECLASSIFICATION/DOWNGRADING SCHEDULE

3 DISTRIBUTION/AVAILABILITY OF REPORT

Approved for public release; distribution is unlimited.

4 PERFORMING ORGANIZATION REPORT NUMBER(S)

AH

5 MONITORING ORGANIZATION REPORT NUMBER(S)

6a NAME OF PERFORMING ORGANIZATION

Naval Ocean Systems Center

6b OFFICE SYMBOL  
(if applicable)

7a NAME OF MONITORING ORGANIZATION

6c ADDRESS (City, State and ZIP Code)

San Diego, CA 92152-5000

7b ADDRESS (City, State and ZIP Code)

8a NAME OF FUNDING SPONSORING ORGANIZATION

Commander Sub Force Pacific

8b OFFICE SYMBOL  
(if applicable)

9 PROCUREMENT INSTRUMENT IDENTIFICATION NUMBER

8c ADDRESS (City, State and ZIP Code)

U.S. Pacific Fleet  
Pearl Harbor, HI 96860

10 SOURCE OF FUNDING NUMBERS

PROGRAM ELEMENT NO	PROJECT NO	TASK NO	AGENCY ACCESSION NO.
DMN	MR02	SUBPAC	DN088 580

11 (If applicable) Security Classification

Convergence Rate of Codes for Numerical Quadrature Techniques for Classical Ray Tracing

12 PERSONAL AUTHORITY

E.R. Floyd

13a TYPE OF REPORT

Presentation

13b TIME COVERED

FROM \_\_\_\_\_ TO \_\_\_\_\_

14 DATE OF REPORT (Year, Month, Day)

December 1986

15 PAGE COUNT

16 SUPPLEMENTARY NOTATION

17 COSATI CODES

FIELD	GROUP	SUB GROUP

18 SUBJECT TERMS (Continue on reverse if necessary and identify by block number)

raytracing  
Stieltjes measure

19 ABSTRACT (Continue on reverse if necessary and identify by block number)

The estimated residual error (or its bound) for numerical quadratures is usually expressed in terms of a derivative of some order of the integrand or some residual factor of the integrand after factoring out a countable number of zeroes and singularities that occur along the integration path. The order of the derivative is a function of the number of sample points for evaluating the integrand. Regrettably, the magnitudes of these higher order derivatives are difficult enough to estimate for even analytic sound velocity profiles. In practice, observed sound velocity profiles, which are usually given in tabular form and include measurement errors, exacerbate our inability to assess the magnitudes of these higher order derivatives. An estimate of the residual error expressed in terms of a first derivative would be far more practical for both analytic and observed sound velocity profiles.

20 DISTRIBUTION AVAILABILITY OF ABSTRACT

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21 ABSTRACT SECURITY CLASSIFICATION

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22 NAME OF RESPONSIBLE INDIVIDUAL

E.R. Floyd

22b TELEPHONE (include Area Code)

619-225-6851

22c OFFICE SYMBOL

Code 192

DD FORM 1473, 84 JAN

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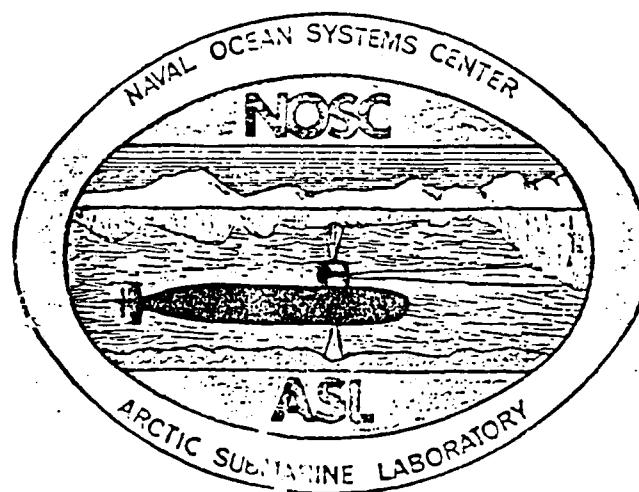
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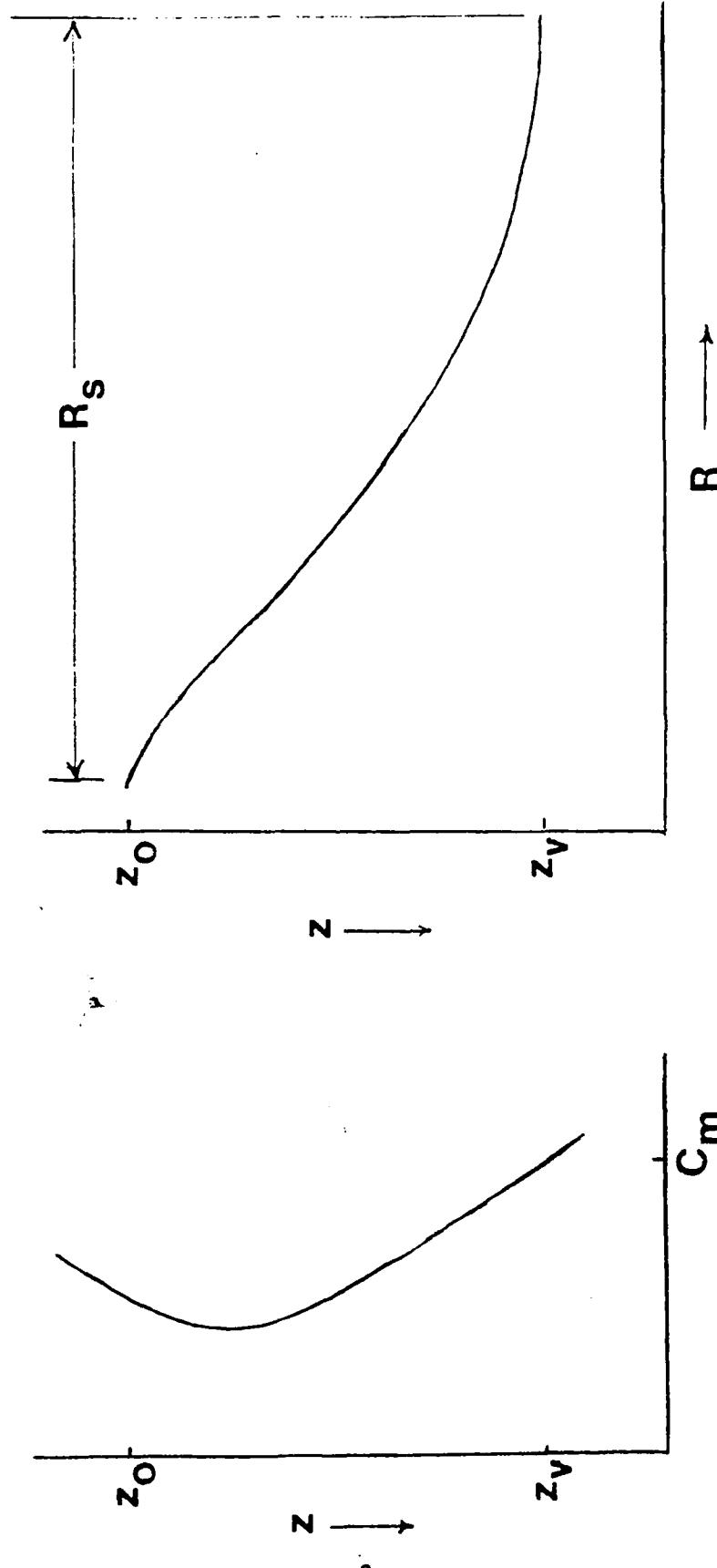
CONVERGENCE RATE OF CODES  
FOR NUMERICAL QUADRATURE TECHNIQUES  
FOR CLASSICAL RAY TRACING

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By classical ray tracing, determine range over a single Riemann sheet for a ray described by the constant of motion (vertex velocity)  $C_m$ . How accurate?



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Range Integral:

$$R_s = \int_{z_0}^{z_v} \frac{C(z)}{[C_m^2 - C^2(z)]^{1/2}} dz$$

$$= \int_{z_0}^{z_v} W(z) f(z) dz$$

W and f are convenient functions of z. [W dz] becomes a Stieltjes measure and f(z), the Stieltjes integrand.

Trick: Choose W(z) to incorporate any poor behavior (singularities or zeros) into W leaving f(z) well behaved.

Thus the Gaussian quadrature

$$R_s \approx (z_v - z_0)^m \sum_{i=1}^n w_{i,n} f(z_{i,n})$$

where:

$n$  is the order of the approximation;

$m$  is determined by  $W$ ;

$w_{i,n}$  is a Gaussian weighting coefficient  
determined by  $W$ ;

$z_{i,n}$  is a Gaussian sample point determined  
by  $W$ .

The Gaussian error is given by

$$\eta_n = \frac{f^{(2n)}(\xi)}{(2n)!} \int_{z_0}^{z_v} w(z) \left[ \prod_{i=1}^n (z - z_{i,n}) \right]^2 dz$$

where  $z_0 \leq \xi \leq z_v$ .

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For underwater acoustics

$$w = (z_v - z)^{-1/2}.$$

Factors out branch point singularity at vertex depth.

Therefore

$$\eta_n = \frac{\pi^{1/2} (z_v - z_0)^{2n+1}}{4n+1} \frac{[(2n)!]^2}{[(4n)!]^2} f^{(2n)}(\xi),$$

$$z_0 \leq \xi \leq z_v.$$

$$\eta_n = \frac{\pi^{1/2} (z_v - z_0)^{2n+1}}{4n+1} \frac{[(2n)!]^3}{[(4n)!]^2} f^{(2n)}(\xi),$$

$$z_0 \leq \xi \leq z_v.$$

---

This expression has several deficiencies;

- Usually impractical to evaluate  $f^{(2n)}$ .
- $f^{(i)}$  for  $i < 2n$  may be discontinuous.
- $C(z)$  is often known only in tabular form.

$$\eta_n = \frac{\pi^{1/2} (z_v - z_0)^{2n+1}}{4n+1} \frac{[(2n)!]^3}{[(4n)!]^2} f^{(2n)}(\xi),$$

$$z_0 \leq \xi \leq z_v.$$

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Analytic (hypothetical)  $C(z)$ :\*

- Rapid convergence with increasing  $n$ .
- Only limited by round-off error.
- Thumb rule for maximum effective  $n$ :

$$n_{\max} \approx ("number of significant figures")/2$$

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\* E. R. Floyd, J. Acoust. Soc. Am. 49, 1580-1590  
(1971)

$$\eta_n = \frac{\pi^{1/2} (z_V - z_0)^{2n+1}}{4n+1} \frac{[(2n)!]^3}{[(4n)!]^2} f^{(2n)}(\xi),$$

$$z_0 \leq \xi \leq z_V.$$

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Observed (nonanalytic)  $C(z)$ :\*

- $C(z)$  tabled at discrete depths.
- Cubic spline fit  $\rightarrow d^3C/dz^3$  discontinuous.  
Nevertheless still rapidly convergent over an assembly of 116 observed  $C(z)$ 's. MOE ---  $\eta$  reduced by a factor of 0.763 for each additional sample point per Riemann sheet.
- Thumb rule for maximum effective  $n$ :

$$n_{\max} \geq \text{"number of significant figures".}$$

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\* E. R. Floyd and J. D. Pugh, J. Acoust. Soc. Am.  
61, 682-687 (1977).

Present Status:

- Even for analytic functions, quadrature errors are difficult to estimate because higher order derivatives are generally complicated.
- While we have convergence rates for an assembly of observed profiles, the discontinuity of higher order derivatives confounds our estimate of convergence for a particular observed profile.

→ Desire an estimate expressed in terms of the first derivative of the Stieltjes integrand.

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